INT-WFC - Astrometric Calibration for the INT Wide Field Camera

User Note
Abstract

Images observed using the Wide Field Camera instrument on the Isaac Newton Telescope contain nonlinear optical distortions. This note gives a quantitative description of these distortions. It also explains how they can be corrected for easily using the CCDPACK package.
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1 Astrometric calibration for INT Wide Field Camera images

The Wide Field Camera instrument on the Isaac Newton Telescope contains four CCD chips of 2048 × 4096 pixels positioned roughly, but not exactly, as shown in figure 1.

In order to do accurate astrometry with data obtained from this instrument, it is necessary to correct for the exact orientation and position of each CCD in relation to the others, as well as for nonlinear distortions away from the optical axis of the focal plane introduced by the optics of the telescope. The nonlinear distortion is very well modelled by a radial “pincushion” transformation, which has the form

\[ r' = r(1 + Dr^2) \]

The following transformations take account of both these effects to map the pixel coordinates \((x_i, y_i)\) of CCD\#i into a new pixel-like coordinate system \((x', y')\) of uniform scale, which is the same for all four CCDs. The origin of this coordinate system is at pixel coordinates \((1778, 3029)\) of CCD\#4, which is taken to be on the optical axis. At this point, one unit of the new coordinate system is equivalent to one pixel of the CCD\#4 system, so that the new coordinates are almost equivalent to CCD\#4 coordinates, although they diverge away from the origin thanks to the nonlinear distortion. Each unit of the new coordinates has the same size, which is approximately 0.333 arcsec.

The corrected coordinates \((x', y')\) are obtained from each set of pixel coordinates \((x_i, y_i)\) by first translating so that the origin is on the optical axis, then rotating to the correct angle, then correcting for the radial distortion effect:

\[
\begin{align*}
    x_i^{\text{shift}} &= x_i - X_i \\
    y_i^{\text{shift}} &= y_i - Y_i \\
    x_i^{\text{rot}} &= x_i^{\text{shift}} \cos \theta_i - y_i^{\text{shift}} \sin \theta_i \\
    y_i^{\text{rot}} &= x_i^{\text{shift}} \sin \theta_i + y_i^{\text{shift}} \cos \theta_i \\
    x' &= x_i^{\text{rot}} \left(1 + D \left[ x_i^{\text{rot}}^2 + y_i^{\text{rot}}^2 \right] \right) \\
    y' &= y_i^{\text{rot}} \left(1 + D \left[ x_i^{\text{rot}}^2 + y_i^{\text{rot}}^2 \right] \right)
\end{align*}
\]
Where \((X_i, Y_i)\) are the coordinates of the optical centre of the instrument in the pixel coordinate system of CCD\#i, \(\theta_i\) is the angle at which CCD\#i sits on the focal plane, and \(D\) is the pincushion distortion coefficient.

Values for these coefficients have been obtained by registering two exposures of the same region of sky, in which the instrument had been rotated by 180° between exposures. The value of \((X_4, Y_4)\) was taken from the value used for the Wide Field Survey data, and \(\theta_4\) was chosen to be zero. The values of the coefficients in these equations are approximately:

\[
\begin{align*}
X_1 &= -336.74 & Y_1 &= 3039.14 & \theta_1 &= 0.01868° \\
X_2 &= 3180.68 & Y_2 &= 1729.67 & \theta_2 &= -90.62115° \\
X_3 &= 3876.73 & Y_3 &= 2996.30 & \theta_3 &= 0.11436° \\
X_4 &= 1778.00 & Y_4 &= 3029.00 & \theta_4 &= 0.00000°
\end{align*}
\]

and

\[
D = -5.30 \times 10^{-10}\text{ pixel}^{-2}
\]

This value of \(D\) corresponds in units of radians to \(-203\text{ rad}^{-2}\), compared to the value \(-259.8\text{ rad}^{-2}\) quoted in the ING observer handbook.

These values of the coefficients are thought to be correct to an accuracy of 1 or 2 pixels, which is around half an arcsecond.

Figure 2 gives an exaggerated representation of the shapes and positions of the CCDs as mapped on to the new coordinate system.
Figure 2: Exaggerated view of the actual arrangement of the CCDs. The dots in the corners mark
the pixel origin for each CCD and the “×” marks the origin of the unified coordinate system.

2 Attaching modified coordinates using CCDPACK

For users of Starlink software, the calibrated coordinate information can be attached auto-
matically to image files using the `ASTIMP` command, and the file `INT-WFC.ast`. This file is
distributed in the CCDPACK package (in directory `$CCDPACK_DIR`, or `bin/ccdpack`).

To use this facility, it is best if the files are first converted to Starlink NDF format using the
`CONVERT` package as follows:

```
% convert
CONVERT commands are now available -- (Version 1.5-4)
Defaults for automatic NDF conversion are set.

Type conhelp for help on CONVERT commands.
Type "showme sun55" to browse the hypertext documentation.

% fits2ndf in='r10628?.fits' out='*' container=true
```

which will convert the FITS file `r106280.fits` into the NDF `r106280.sdf` and so on. The Starlink
software will in fact work with FITS files, but because it converts them on the fly between FITS
and NDF formats before and after each command, this can be rather slow with files the size of
WFC frames.
Once the file is in Starlink NDF format, from the Unix C shell do the following:

```bash
% ccdpack

CCDPACK commands are now available -- (Version 4.0-16)

For help use the commands ccdhelp or ccdwww

% astimp in='r10628?' astfile=$CCDPACK_DIR/INT-WFC.ast reset accept

ASTIMP
=======

Framesets read from file INT-WFC.ast:
  FITS header "ROTSKYPA" used for rotation

<table>
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<th>N</th>
<th>Base domain</th>
<th>Current domain</th>
<th>Frameset ID</th>
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<td>1</td>
<td>PIXEL</td>
<td>INT-WFC</td>
<td>FITSID CHIPNAME 'A5506-4'</td>
</tr>
<tr>
<td>2</td>
<td>PIXEL</td>
<td>INT-WFC</td>
<td>FITSID CHIPNAME 'A5383-17-7'</td>
</tr>
<tr>
<td>3</td>
<td>PIXEL</td>
<td>INT-WFC</td>
<td>FITSID CHIPNAME 'A5530-3'</td>
</tr>
<tr>
<td>4</td>
<td>PIXEL</td>
<td>INT-WFC</td>
<td>FITSID CHIPNAME 'A5382-1-7'</td>
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</tbody>
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4 NDFs accessed using parameter IN

Processing NDF /data/cass58a/mbt/data/int4/r106280
  Matched with frameset ID "FITSID CHIPNAME 'A5506-4'"
  Rotating additional 180 degrees
  New frame in domain "INT-WFC" added

Processing NDF /data/cass58a/mbt/data/int4/r106281
  Matched with frameset ID "FITSID CHIPNAME 'A5383-17-7'"
  Rotating additional 180 degrees
  New frame in domain "INT-WFC" added

Processing NDF /data/cass58a/mbt/data/int4/r106282
  Matched with frameset ID "FITSID CHIPNAME 'A5530-3'"
  Rotating additional 180 degrees
  New frame in domain "INT-WFC" added

Processing NDF /data/cass58a/mbt/data/int4/r106283
  Matched with frameset ID "FITSID CHIPNAME 'A5382-1-7'"
  Rotating additional 180 degrees
  New frame in domain "INT-WFC" added
```

This command sets the Current coordinate frame of the specified NDF files to the new coordinate system \((x', y')\) described above. As well as applying the linear and nonlinear geometry terms whose coefficients were given, it also rotates the coordinates according to the value of the ROTSKYPA FITS header card, which records the orientation of the turntable when the observation was made; in this case it was oriented at 180°. In this way, applying the INT-WFC.ast file to any set of image NDF files will result in them sharing coordinates which are related by a simple shift in X and Y coordinates, since the nonlinear optical distortions, the exact positioning of the CCDs on the turntable, and the orientation of the turntable itself will have been accounted for.

Once the new coordinate system has been attached to the images, then most Starlink applications
Figure 3: Display of a single CCD image with coordinates grafted onto it using ASTIMP. Close inspection will show that the grid is not quite parallel to the sides of the image, or straight, because of the slight rotation from the vertical and nonlinear distortion.

will make use of this as appropriate. If you display any of the images using KAPPA's DISPLAY application, the axes will show the coordinates in the new frame as in figure 3:

```
% kappa

KAPPA commands are now available -- (Version 0.13-7)

Type kaphelp for help on KAPPA commands
Type "showme sun95" to browse the hypertext documentation

% display r106282 style='"grid=1,gap=500"'
```

If some of the frames overlap, the corresponding X and Y offsets can then easily be determined using CCDPACK’s object matching registration facilities.

### 3 Acknowledgements

This calibration was done on Starlink time with assistance from Peter Draper and David Gilbank in Durham.